Classical Gram-Schmidt without Reorthogonalization

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Classical Gram-Schmidt: [Q, R] = CGS(A)Input: $A = [a_1, a_2, ..., a_n] \in \mathbb{R}^{m \times n}$, full column rank Output: Q, R : A = QR, $Q^T Q = I$, R upper triangular

$$\rho = ||a_1||_2$$

$$Q = [a_1/\rho], \quad R = [\rho]$$
For j=2:n
$$r = Q^T a_j$$

$$s = a_j - Qr$$

$$\rho = ||s||_2$$

$$Q = [Q \ s/\rho], \quad R = \begin{bmatrix} R & r \\ 0 & \rho \end{bmatrix}$$
EndFor

$$A \in \mathbb{R}^{m imes n}, \ m \ge n$$
, full rank.

In exact arithmetic:

$$A = \mathcal{QR}, \quad \mathcal{Q} \in \mathbb{R}^{m \times n}, \quad \mathcal{Q}^{\mathcal{T}} \mathcal{Q} = I, \quad \mathcal{R} = \left[\bigtriangledown \right] \in \mathbb{R}^{n \times n}$$

In finite precision:

$$A = QR + F, \quad R = \left[\bigtriangledown \right]$$

• Q and R are the *computed* factors,

• The residual F is small (for CGS $||F||_2 \le (2^{3/2}mn + 2n^{1/2})||A||_2 \mathbf{u})$.

Image: A = A

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Theorem: If the (thin) QR factorization A = QR is computed with CGS and R is column-diagonally dominant, then

$$\|I - Q^{\mathsf{T}}Q\|_{\mathsf{F}} \leq 3mn^{3/2}\kappa_{\mathsf{F}}(\mathsf{R})\mathbf{u} + \mathcal{O}(\mathbf{u}^2).$$

Proof: sketched in next few slides...

In the notation of the CGS algorithm above, R is "column-diagonally dominant" iff $||r||_1 \le \rho$ at each step.

 $\kappa_F(R) \equiv \|R\|_F \|R^{-1}\|_F$

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Q is *numerically* invariant under column scaling of A:

If $D = \text{diag}(d_1, d_2, \dots, d_n), \ d_{1:n} \neq 0$, and AD = QU is a QR factorization, then

$$A = Q(UD^{-1}) \equiv QR$$
 is a QR factorization of A.

To simplify discussion of the error analysis^{*}, we will assume $||Ae_i||_2 = 1$.

Now $||F||_2 \leq (3mn + 2n^{1/2})\mathbf{u}$ is slightly cleaner than $||F||_2 \leq (3mn + 2n^{1/2})||A||_2\mathbf{u}$, since $||A||_2$ was a simplifying bound on $||a_j||_2$.

*The scaling doesn't need to be implemented for the results to hold (e.g., our code uses a base-2 scaling simply to avoid overflow possibilities...).

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We are interested in $||E|| = ||I - Q^T Q||$, and thus consider

$$R - Q^T A = R - Q^T (QR + F) = (I - Q^T Q)R - Q^T F = ER - Q^T F:$$

For CGS, $sut(R) \equiv sut(fl(Q^T A))$, so

$$\mathsf{sut}(\mathsf{ER}) = \mathsf{sut}(\mathsf{Q}^\mathsf{T}\mathsf{F})$$

We will use *ER* (actually $R^T E$) to bound ||E||.

This shares some similarity with Giraud's (Giraud et al., 2005) analysis (almost) showing that CGS loss of orthogonality was proportional to $\kappa^2(A)$, and Smoktunowicz's "rescue" (Smoktunowicz et al., 2006); those papers use $R^T E R \approx R^T R - A^T A$ rather than $R^T E$ to bound ||E||.

At end of step k+1:
$$R_{k+1} = \begin{bmatrix} R & r \\ 0 & \rho \end{bmatrix}$$
, $||r||_2 \le ||r||_1 \le \rho \le 1$,
 $E_{k+1} \equiv I - Q_{k+1}^T Q_{k+1} = \begin{bmatrix} E & (f - Er)/\rho \\ (f - Er)^T/\rho & \rho(1 - q^T q) \end{bmatrix}$,

- E and Er/ρ are the price we pay in this step for loss of orthogonality in the previous steps.
- f/ρ and $\rho(1 q^T q)$ are rounding errors from this step (local error).

$$R_{k+1}^{T} E_{k+1} = \begin{bmatrix} R^{T} & -R^{T} Er/\rho \\ 0 & -r^{T} Er/\rho \end{bmatrix} + G,$$
$$\|G\|_{2} = \| \begin{bmatrix} 0 & R^{T} f/\rho \\ f^{T}/\rho & r^{T} f/\rho + \rho(1-q^{T}q) \end{bmatrix} \|_{2} \le \sqrt{2} \|F\|_{2}.$$

$$R_{k+1}^{\mathsf{T}} E_{k+1} = \begin{bmatrix} R^{\mathsf{T}} & -R^{\mathsf{T}} E r/\rho \\ 0 & -r^{\mathsf{T}} E r/\rho \end{bmatrix} + G, \quad ||r||_1 \le \rho$$

We can bound the last column of $R_{k+1}^T E_{k+1}$:

• $\|R^T Er/\rho\|_2 \le \max_{\|r\|_1=1} \|R^T Er\|_2 \equiv \|R^T E\|_{2,1} = \max_j \|R^T Ee_j\|_2$ • $r^T Er/\rho = (\|a\|_2^2 - \|r\|_2^2 - \rho^2 + \text{local error})/\rho$, (recall: $\rho \ge 2^{-1/2}$)

...and thus $\|R_{k+1}^T E_{k+1}\|_{2,1} \le \|R^T E\|_{2,1} + \text{local error}$ Finally,

$$||E||_{F} = ||R^{-T}R^{T}E||_{F} \le ||R^{-T}||_{F} ||R^{T}E||_{F}$$

$$\le ||R^{-1}||_{F} \sqrt{n} ||R^{T}E||_{21} \le (||R^{-1}||_{F} ||R||_{F}) 4mn^{3/2} \mathbf{u} + O(\mathbf{u}^{2})$$

Selective Reorthogonalization Criteria

$$\begin{split} \rho &= ||a_1||_2, \quad Q = [a_1/\rho], \quad R = [\rho] \\ \text{For } j = 2:n \\ r &= Q^T a_j, \quad s = a_j - Qr, \quad \rho = ||s||_2 \\ \text{If } \text{reort}(\rho, ||r||, \text{tol}) \\ u &= Q^T s, \quad r = r + u, \quad s = s - Qu, \quad \rho = ||s||_2 \\ \text{End} \\ Q &= [Q \quad s/\rho], \quad R = \left[\begin{array}{c} R & r \\ 0 & \rho \end{array} \right] \\ \text{FordEor} \end{split}$$

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Historically, reort(ρ , ||r||, tol) has looked like

$$\|r\|_2 > K
ho$$
, with $tol = K = 2^{-1}$ or $2^{-1/2}$ or 1 or 2 or 10 or ...

More recently (2003, Giraud & Langou (in MGS context)) suggested

$$||r||_1 > L\rho$$
, with $L < 1$.

N.B. $||r||_1 \leq \rho$ is column-diagonal dominance in $R \dots$

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...But don't reorthogonalize:

The next few algorithms will have a structure like CGS with selective reorthogonalization. Rather than reorthogonalize, we use Giraud's L-criterion to partition.

This can be set in Carson's (Carson et al., 2022) Block Gram-Schmidt (BGS) framework, but with variable block sizes. In their language intra-ortho ("muscle") is CGS, and inter-ortho ("skeleton") is BGS.

The methods we present are BLAS2 versions, not taking advantage of BLAS3 speedup nor flexibility. For example, the BGS inter-ortho consists of matrix-matrix products, while the methods we will present compute these matrix-matrix products as a collection of matrix-vector multiplies.

$$\begin{split} & [Q, R, P] = \mathsf{CGSReject}(A) \\ & \mathsf{Input:} \ A = [a_1, a_2, \dots, a_n] \in \mathbb{R}^{m \times n}, \ \mathsf{full \ column \ rank} \\ & \mathsf{Output:} \ Q, R, P : AP = [Q_1 R_1, \ Q_1 R_2 + Q_2], \ Q_1^T Q_1 = I, \ R_1 \ \mathsf{upper}, \ P \ \mathsf{perm} \\ & \rho = ||a_1||_2, \ Q_1 = [a_1/\rho], \ R_1 = [\rho] \\ & \mathsf{For \ j=2:n} \\ & r = Q^T a_j, \ s = a_j - Qr, \ \rho = ||s||_2 \\ & \mathsf{If} \ ||r||_1 \leq L\rho, \\ & Q_1 = [Q_1 \ s/\rho], \ R_1 = \left[\begin{array}{c} R_1 \ r \\ 0 \ \rho \end{array} \right] \ (\mathsf{accepted}) \\ & \mathsf{Else,} \\ & Q_2 = [Q_2 \ s], \ R_2 = \left[\begin{array}{c} R_2 \ r \\ 0 \ 1 \end{array} \right] \ (\mathsf{rejected}) \end{split}$$

End

Update rejected columns (Q_2 and R_2) by those subsequently accepted* EndFor

% Adding recursion below would give $AP=QR,\ R$ "psychologically" triangular %If any rejected,

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% [Qnew, Rnew, Pnew] = CGSReject(Q<sub>2</sub>)
% Update Q, R, P with Qnew, Rnew, Pnew
%End
```

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$$AP = QR$$

R "psychologically upper triangular" (old term): Just means that *R* is permutation equivalent to a triangular matrix. In fact AP = QR gives the QR-factorization of *A* as

$$A = (QP) (P^T RP).$$

This means, e.g. that we can use CGSReject as an Intra-Ortho BGS method.

Update rejected columns (Q_2 and R_2) by those subsequently accepted

After a pass of CGSR eject the columns of Q have been partitioned as

$$Q_1 = [q_{a_1}, q_{a_2}, \dots, q_{a_{n_a}}]$$
 and $Q_2 = [q_{r_1}, q_{r_2}, \dots, q_{r_{n_r}}]$

Each q_{r_i} has associated with it a (possibly empty) set of q_{a_j} for which it has "missed" the orthogonalization, namely all q_{r_i} for which $r_i < a_j$. Name these $q_{a_1}, \ldots, q_{a_{j(i)}}$. There are at least 2 obvious ways to update:

CGS update:
For i=
$$r_1, \ldots, r_{n_r}$$
,
 $V = [q_{a_1}, \ldots, q_{a_{j(i)}}]$, $rr = V' * q_{r_i}$, $q_{r_i} = q_{r_i} - V * R(r_1, \ldots, b_{r_{j(i)}}, b_i) = rr$
End
MGS (row) update:
For j= a_1, \ldots, a_{n_a} ,
 $V = [q_{r_1}, \ldots, q_{r_{i(j)}}]$, $rr = r(j, r_1, \ldots, r_{j(i)})$
 $rr = q'_{a_j} * V$, $[q_{r_1}, \ldots, q_{r_{i(j)}}] = V - q_{a_j} rr$
End

rr,

C2MGS

$$A = [Q_1, Q_2, \dots, Q_K] \begin{bmatrix} R_{11} & R_{12} & \dots & R_{1K} \\ & R_{22} & \dots & R_{2K} \\ 0 & & \ddots & R_{KK} \end{bmatrix}$$

 $Q_j \in \mathbb{R}^{m \times n_j}$, $R_{ij} \in \mathbb{R}^{n_i \times n_j}$, and n_j , $j=1:\kappa$, are determined at runtime by L-criterion

- $L \rightarrow 0$: pure MGS (row-implementation)
- $L \to \infty$: pure CGS
- Analysis not done, but we believe that with L = 1, this would be a backward stable orthogonalization for Krylov methods, like, e.g. Arnoldi or GMRes

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$$\begin{split} & [Q, R, Blks] = \mathsf{C2MGS}(A) \\ & \text{Input: } A = [a_1, a_2, ..., a_n] \in \mathbb{R}^{m \times n}, \text{ full column rank} \\ & \text{Output: } Q, R : A = QR, Q^T Q = I, R \text{ upper}, Blks : indices into blocks} \\ & r_{11} = ||a_1||_2, V = [a_1/r_{11}], R_1 = [r_{11}], K = 1, CurBlkSiz = 1 \\ & \text{For } j=2:n \\ & w = a_j \\ & \text{For } k = 1:K-1 \\ & (Block MGS \text{ on current column}) \\ & r(Blks_k) = Q_k^T w, w = w - Q_k r \\ & \text{End} \\ & r(CurBlk) = V^T w, s = w - Vw, r_{jj} = \rho = ||w||_2 \\ & \text{If } ||r||_1 \leq L\rho, \\ & ++CurBlkSiz, CurBlk = [CurBlk j] \\ & V = [V \ s/\rho] \\ & \text{Else,} \\ & ++K, Blks_K = CurBlk \\ & Q_K = V, V = [w] \\ & \text{End} \end{split}$$

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All computational examples presented here were done on my desktop (Dell Precision 2480, Matlab 2022a) or the Mac laptop of Caroline Jennings.

Caroline is graduating in the next few days with Honors and with majors in Mathematics and Creative Writing. She has been working with CGS/MGS just for fun!

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